Behavioral Type Inference for Concurrent Object-Oriented Languages

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Problem

Large-scale software systems rely on communication protocols

Mainstream programming languages do not cope with them:

- **provide (some) data-type safety**
- \blacksquare fail to give static support to stateful behaviour

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 \blacksquare fail to give static support to stateful behaviour

Most (static) approaches to code correctness not well suited

Usual safety quarantees not enough: An application that allows to open and close a file, but not read or write, is safe but not useful

Liveness is hard to statically verify (sometimes not possible)

Several approaches to analyse code

- Deductive proof systems
- **Model-checkers / Abstract Interpretation**
- \blacksquare Type systems

We aim at an *automatic, decidable, tool, coping with safety and (weak) liveness properties* (like protocol completion)

The Mool Language: <http://gloss.di.fc.ul.pt/mool>

- Small, rigorously defined, Java-like, and object-oriented
- Associates with each class a behavioural type
- Types express valid sequences of method calls
- Type system ensures statically safe usage of objects' protocols

We will work with a new version of the language

- **E** Aspects where the language was incorrect or too restricting were revised
	- Concurrency
	- Use of *null* as a value
	- Shared usages
	- ...
- **Assertions were added**
	- Boolean expressions on the state of fields and parameters

The problem we address

Observations

- Specifying objects intended behaviour as state machines is natural, but may be demanding and not easy to get right
- Stating, for each method, the required and ensured state of fields and parameters may be easier
- Assertions are part of Java since 2006

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- Specifying objects intended behaviour as state machines is natural, but may be demanding and not easy to get right
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- Assertions are part of Java since 2006

Question

Can we get behavioural types from code with assertions?

Infer, from O.-O. code with assertions, behavioural (class) types ensuring safe interoperability

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Infer, from O.-O. code with assertions, behavioural (class) types ensuring safe interoperability

A type inference system: given a program

EX either fails: the code is *not well-typed* (in the standard sense) or it may produce a run-time error due to calling methods in an *incorrect order*;

n or returns a new version of the code with the classes annotated with behavioural types, ensuring *object interoperability*.

The process is composed by three stages

1 Typestate generation

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- **1** Typestate generation
- **2** Usage generation

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- **1** Typestate generation
- **2** Usage generation
- **3** Object usage state inference

Input example - *File* class

```
class File {
```

```
int linesInFile; int linesRead;
boolean closed; boolean line In Buffer; boolean is Eqf;
```

```
\frac{1}{2} //@invariant linesRead >= 0 && linesRead <= linesInFile:
\frac{1}{2} milion lines Read == 0 && lines In File == 5
            && !closed && !lineInBuffer && !isEof;
void File () { ... }
```
}

. . .

Input example - *File* class

. . .

. . .

```
class File {
```

```
//@requires linesRead < linesInFile && !closed && lineInBuffer
           && !isEof;
\frac{1}{2} //@ensures linesRead + 1 <= linesInFile
           && !closed && !lineInBuffer && !isEof;
string read () \{ \ldots \}
```
Input example - *File* class

. . .

. . .

```
class File {
```

```
//@requires linesRead <= linesInFile && !closed && !lineInBuffer
          && !isEof;
//@ensures (linesRead == linesInFile -> !lineInBuffer && isEof)
          && !closed;
boolean eof() { ... }
```
. . .

Input example - *File* class

```
class File {
```

```
\pi //@requires linesRead == linesInFile && isEof && !closed;
//@ensures linesRead == linesInFile && isEof && closed;
void close() {
          clo sed = t rue ;
}
```
Based on the algorithm presented in

G. D. Caso, V. Braberman, D. Garbervetsky, and S. Uchitel. "Enabledness-based Program Abstractions for Behavior Validation". In: ACM Trans. Softw. Eng. Methodol. 22.3 (July 2013), 25:1–25:46. ISSN: 1049-331X

- **Enabledness-preserving automata extraction from source** code equipped with assertions
- \blacksquare We modified the algorithm to apply it in code with preconditions and postconditions
- We then use a SMT solver to perform the validity checks

Choice-based transitions

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- \blacksquare The algorithm allows nondeterministic transitions with multiple target states

Mool depends on the result of *eof* to know which state to transit to

The original algorithm produces the following transition relation

$$
\delta(S_a,m)=S_b
$$

Meaning that, when executing the method *m* in state *Sa*, the object transits to state *Sb*.

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Meaning that, when executing the method *m* in state *Sa*, the object transits to state *Sb*.

In a nondeterministic context it is possible to have the following transition relation:

$$
(S_a, m, S_{b_1}) \in \delta
$$

\n
$$
(S_a, m, S_{b_2}) \in \delta
$$

\nWhere S_{b_1} and S_{b_2} are different states.

In our version the transition relation is *a function*, defined as follows

 $\delta(S_a, m, c) = S_b$

Where *c* is the choice the transition corresponds to.

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Where *c* is the choice the transition corresponds to. In the previous nondeterministic example, the transition relation could be:

$$
\delta(S_a, m, \text{false}) = S_{b_1}
$$

$$
\delta(S_a, m, \text{true}) = S_{b_2}
$$

Meaning that, if *m* returns *true* the object transits to state $\mathcal{S}_{b_2},$ otherwise it transits to state $\mathcal{S}_{b_{1}}.$

Transition relation extension

- \blacksquare To do this, the algorithm needs to know which state corresponds to both true and false branches
- \blacksquare The post-condition must specify the object state in both choices

Output example - Typestate of the *File* class

Based on the algorithm presented in

P. Collingbourne and P. H. J. Kelly. "Inference of Session Types From Control Flow". In: Electron. Notes Theor. Comput. Sci. 238.6 (June 2010), pp. 15–40. ISSN: 1571-0661.

- Session type inference for C
- We are only interested in stage three of the algorithm: Graph Simplification and Translation

Stage 2 - Usage generation

Choice-based transitions

- The translation function does not deal with choice-based transitions
- We extend it so that it translates these type of transitions into variant types

$$
\delta(S_a, m, \text{false}) = (S_{b_1})
$$
\n
$$
\delta(S_a, m, \text{true}) = (S_{b_2})
$$
\n
$$
\Rightarrow S_a = \{m; < S_{b2} + S_{b1} > \}
$$

Shared state of usage states

- An usage state can be defined as shared or non-shared
- We extend the translation function to infer the shared status of an usage state
- An usage state is considered shared if:
	- \blacksquare Its completely recursive

$$
S_a=\{a;S_a+b;S_a\}
$$

It only transits to equivalent usage states

$$
S_a = \{a; S_a + b; S_b\} \qquad S_b = \{a; S_b + b; S_a\}
$$

Output example - Usage of the *File* class

```
usage lin { File : Q1 } where
              Q1 = \text{lin} \{ \text{eof} : \langle Q2 + Q3 \rangle \}Q3 = \text{lin} \{ \text{read} : Q1 \}Q2 = \text{lin} \{ \text{close} : \text{end} \}
```
Specifying the initial usage state of fields

Mool offers the possibility of indicating the state of the usage of a object in its declaration:

```
class FileReader {
             . . .
            F i l e [ Q3 ] f i l e ;
             . . .
}
```
Specifying the usage state of parameters

. . .

Programmers can also define the usage state of parameters:

```
void FileReader (File [Q3] f) {
         file = f:
```
Specifying the usage state of a returned object

 \blacksquare It is also possible to define the usage state of an object returned by a method:

```
File [Q3] getFileToRead() {
        file:
}
```
Usage state declaration in the context of our work

- We do not expect the programmer to know beforehand the states that will compose the generated usage
- \blacksquare But we can expect the programmer to know the state of an object when initialised

Using preconditions to specify the state of an object

```
\blacksquare It is possible to express the expected state of the instance
  received as a parameter in the precondition of the method:
```

```
class FileReader {
        File file:...
```
. . .

```
\pi/2 (@invariant counter \epsilon= 0:
//@requires f = null && If.eof();
\frac{1}{2} (@initial counter == 0 && new File() && lisEof;
void FileReader (File f) { file = f; ... }
```
Using preconditions to specify the state of an object

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\blacksquare It is possible to express the expected state of the instance
  received as a parameter in the precondition of the method:
```

```
class FileReader {
        File file:...
```

```
\pi/2 (@invariant counter \epsilon= 0:
//@requires f != null && !f.eof();
\frac{1}{2} (@initial counter == 0 && new File() && !isEof;
void FileReader (File \begin{bmatrix} \mathbf{Q3} \end{bmatrix} f) { file = f; ... }
```
Using preconditions to specify the state of an object

 \blacksquare It is also possible to know the initial state of an object when it is initialized:

```
class FileReader {
           File [Q3] file; \ldots\frac{1}{2} (@invariant counter \geq 0:
          //@requires f = null && If.eof();
          //@initial counter == 0.88 new File() 8.8 lisEof;
           void FileReader (File [Q3] f) { file = f; ... }
```
Using postconditions to specify the state of a returned object

This usage state can be inferred using the method postcondition to express the expected state of the returned object:

```
//@requires !isEof;
//@ensures !isEof && !file.eof();
File getFileToRead() {
          file :
}
```
Using postconditions to specify the state of a returned object

This usage state can be inferred using the method postcondition to express the expected state of the returned object:

```
//@requires !isEof;
//@ensures !isEof && !file.eof();
File [Q3] getFileToRead() {
          file :
}
```
Algorithm steps

- **1** Determines the usage state of every parameter using the preconditions
- **2** Analyses the code of the method and:
	- For every initialization, sets the usage state of the initialized variable with the usage state of the value
	- For every call, changes the current usage state of the object the method was called
- **3** Determines the usage state of the return type using the postconditions

Work summary

 \blacksquare In short, the algorithm does the following:

- Generates typestates from the code equipped with assertions
- \blacksquare Translates the typestates into usage types
- Infers the correct usage state for each declared object

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 \blacksquare In short, the algorithm does the following:

- Generates typestates from the code equipped with assertions
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- Infers the correct usage state for each declared object
- We implemented the algorithm:

<http://usinfer.sourceforge.net/>

Conclusion

Assertions

- If the assertions are not correct, one of two things might happen:
	- \blacksquare The tool fails to infer the usage types
	- The tool produces usage types that may allow unwanted behaviour \blacksquare In that case, typechecking the code with such usage may fail, if it allows erroneous behaviour

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- If the assertions are not correct, one of two things might happen:
	- \blacksquare The tool fails to infer the usage types
	- The tool produces usage types that may allow unwanted behaviour In that case, typechecking the code with such usage may fail, if it allows erroneous behaviour
- \blacksquare Thus, the algorithm can also be used to verify the correctness of the assertions

Future work

Correctness

We want to:

- State the intended results
- **Prove the algorithm sound**

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We want to:

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Assertions

Programming with assertions is also hard

■ We want to infer them as automatically as possible

Thank you