Behavioral Type Inference for Concurrent Object-Oriented Languages

Cláudio Vasconcelos

Master thesis presentation

NOVA-LINCS and Dep. de Informática, FCT Universidade NOVA de Lisboa

Advised by Professor António Ravara

November 28, 2016

Problem

Large-scale software systems rely on communication protocols

Mainstream programming languages do not cope with them:

- provide (some) data-type safety
- fail to give static support to stateful behaviour

Problem

Large-scale software systems rely on communication protocols

Mainstream programming languages do not cope with them:

- provide (some) data-type safety
- fail to give static support to stateful behaviour

Most (static) approaches to code correctness not well suited

 Usual safety guarantees not enough: An application that allows to open and close a file, but not read or write, is safe but not useful

Liveness is hard to statically verify (sometimes not possible)

Several approaches to analyse code

- Deductive proof systems
- Model-checkers / Abstract Interpretation
- Type systems

We aim at an *automatic, decidable, tool, coping with safety and (weak) liveness properties* (like protocol completion)

The Mool Language: http://gloss.di.fc.ul.pt/mool

- Small, rigorously defined, Java-like, and object-oriented
- Associates with each class a behavioural type
- Types express valid sequences of method calls
- Type system ensures statically safe usage of objects' protocols

We will work with a new version of the language

- Aspects where the language was incorrect or too restricting were revised
 - Concurrency
 - Use of *null* as a value
 - Shared usages
 - **...**
- Assertions were added
 - Boolean expressions on the state of fields and parameters

The problem we address

Observations

- Specifying objects intended behaviour as state machines is natural, but may be demanding and not easy to get right
- Stating, for each method, the required and ensured state of fields and parameters may be easier
- Assertions are part of Java since 2006

The problem we address

Observations

- Specifying objects intended behaviour as state machines is natural, but may be demanding and not easy to get right
- Stating, for each method, the required and ensured state of fields and parameters may be easier
- Assertions are part of Java since 2006

Question

Can we get behavioural types from code with assertions?

Infer, from O.-O. code with assertions, behavioural (class) types ensuring safe interoperability

Infer, from O.-O. code with assertions, behavioural (class) types ensuring safe interoperability

A type inference system: given a program

either fails: the code is *not well-typed* (in the standard sense)

Infer, from O.-O. code with assertions, behavioural (class) types ensuring safe interoperability

A type inference system: given a program

either fails: the code is not well-typed (in the standard sense) or it may produce a run-time error due to calling methods in an incorrect order;

Infer, from O.-O. code with assertions, behavioural (class) types ensuring safe interoperability

A type inference system: given a program

either fails: the code is not well-typed (in the standard sense) or it may produce a run-time error due to calling methods in an incorrect order;

or returns a new version of the code with the classes annotated with behavioural types, ensuring *object interoperability*.

The process is composed by three stages

Typestate generation

The process is composed by three stages

- Typestate generation
- 2 Usage generation

The process is composed by three stages

- Typestate generation
- 2 Usage generation
- Object usage state inference

Input example - File class

```
class File {
```

```
int linesInFile; int linesRead;
boolean closed; boolean lineInBuffer; boolean isEof;
```

```
//@invariant linesRead >= 0 && linesRead <= linesInFile;
//@initial linesRead == 0 && linesInFile == 5
    && !closed && !lineInBuffer && !isEof;
void File() { ... }
```

Input example - *File* class

. . .

```
class File {
```

Input example - *File* class

. . .

```
class File {
```

Input example - *File* class

```
class File {
```

Based on the algorithm presented in

G. D. Caso, V. Braberman, D. Garbervetsky, and S. Uchitel. "Enabledness-based Program Abstractions for Behavior Validation". In: ACM Trans. Softw. Eng. Methodol. 22.3 (July 2013), 25:1–25:46. ISSN: 1049-331X

- Enabledness-preserving automata extraction from source code equipped with assertions
- We modified the algorithm to apply it in code with preconditions and postconditions
- We then use a SMT solver to perform the validity checks

Choice-based transitions

Mool allows transitions to have, at most, two target states, with these being based on choice

Choice-based transitions

- Mool allows transitions to have, at most, two target states, with these being based on choice
- The algorithm allows nondeterministic transitions with multiple target states



Choice-based transitions

- Mool allows transitions to have, at most, two target states, with these being based on choice
- The algorithm allows nondeterministic transitions with multiple target states



Mool depends on the result of *eof* to know which state to transit to

The original algorithm produces the following transition relation

$$\delta(S_a, m) = S_b$$

Meaning that, when executing the method m in state S_a , the object transits to state S_b .

The original algorithm produces the following transition relation

$$\delta(S_a, m) = S_b$$

Meaning that, when executing the method m in state S_a , the object transits to state S_b .

In a nondeterministic context it is possible to have the following transition relation:

 $(S_a, m, S_{b_1}) \in \delta$ $(S_a, m, S_{b_2}) \in \delta$ Where S_{b_1} and S_{b_2} are different states.

In our version the transition relation is *a function*, defined as follows

$$\delta(S_a, m, c) = S_b$$

Where *c* is the choice the transition corresponds to.

In our version the transition relation is *a function*, defined as follows

 $\delta(S_a, m, c) = S_b$

Where c is the choice the transition corresponds to. In the previous nondeterministic example, the transition relation could be:

 $\delta(S_a, m, false) = S_{b_1}$ $\delta(S_a, m, true) = S_{b_2}$

Meaning that, if *m* returns *true* the object transits to state S_{b_2} , otherwise it transits to state S_{b_1} .

Transition relation extension

- To do this, the algorithm needs to know which state corresponds to both true and false branches
- The post-condition must specify the object state in both choices

Output example - Typestate of the File class



Based on the algorithm presented in

P. Collingbourne and P. H. J. Kelly. "Inference of Session Types From Control Flow". In: Electron. Notes Theor. Comput. Sci. 238.6 (June 2010), pp. 15–40. ISSN: 1571-0661.

- Session type inference for C
- We are only interested in stage three of the algorithm: Graph Simplification and Translation

Stage 2 - Usage generation

Choice-based transitions

- The translation function does not deal with choice-based transitions
- We extend it so that it translates these type of transitions into variant types

$$egin{aligned} &\delta(S_a,\textit{m},\textit{false}) = (S_{b_1}) \ &\delta(S_a,\textit{m},\textit{true}) = (S_{b_2}) \end{aligned} \implies S_a = \{\textit{m}; < S_{b2} + S_{b1} > \} \end{aligned}$$

Stage 2 - Usage generation

Shared state of usage states

- An usage state can be defined as shared or non-shared
- We extend the translation function to infer the shared status of an usage state
- An usage state is considered shared if:
 - Its completely recursive

$$S_a = \{a; S_a + b; S_a\}$$

It only transits to equivalent usage states

$$\mathcal{S}_a = \{ a; \, \mathcal{S}_a + b; \, \mathcal{S}_b \} \qquad \mathcal{S}_b = \{ a; \, \mathcal{S}_b + b; \, \mathcal{S}_a \}$$

Output example - Usage of the File class

```
usage lin { File ; Q1 } where
    Q1 = lin { eof ; < Q2 + Q3 >}
    Q3 = lin { read ; Q1 }
    Q2 = lin { close ; end };
```

Specifying the initial usage state of fields

Mool offers the possibility of indicating the state of the usage of a object in its declaration:

```
class FileReader {
...
File[Q3] file;
...
}
```

Specifying the usage state of parameters

. . .

Programmers can also define the usage state of parameters:

```
void FileReader(File[Q3] f) {
    file = f;
```

Specifying the usage state of a returned object

It is also possible to define the usage state of an object returned by a method:

```
File[Q3] getFileToRead() {
    file;
}
```

Usage state declaration in the context of our work

- We do not expect the programmer to know beforehand the states that will compose the generated usage
- But we can expect the programmer to know the state of an object when initialised

Using preconditions to specify the state of an object

```
It is possible to express the expected state of the instance
received as a parameter in the precondition of the method:
```

```
class FileReader {
File file; ...
```

```
//@invariant counter >= 0;
//@requires f != null && lf.eof();
//@initial counter == 0 && new File() && lisEof;
void FileReader(File f) { file = f; ... }
```

Using preconditions to specify the state of an object

```
It is possible to express the expected state of the instance
received as a parameter in the precondition of the method:
```

```
class FileReader {
File file; ...
```

```
//@invariant counter >= 0;
//@requires f != null && !f.eof();
//@initial counter == 0 && new File() && !isEof;
void FileReader(File[Q3] f) { file = f; ... }
```

Using preconditions to specify the state of an object

It is also possible to know the initial state of an object when it is initialized:

```
class FileReader {
    File[Q3] file; ...
    //@invariant counter >= 0;
    //@requires f != null && !f.eof();
    //@initial counter == 0 && new File() && !isEof;
    void FileReader(File[Q3] f) { file = f; ... }
```

Using postconditions to specify the state of a returned object

This usage state can be inferred using the method postcondition to express the expected state of the returned object:

```
//@requires lisEof;
//@ensures lisEof && lfile.eof();
File getFileToRead() {
    file;
}
```

Using postconditions to specify the state of a returned object

This usage state can be inferred using the method postcondition to express the expected state of the returned object:

```
//@requires !isEof;
//@ensures !isEof && !file.eof();
File [Q3] getFileToRead() {
    file;
}
```

Algorithm steps

- Determines the usage state of every parameter using the preconditions
- 2 Analyses the code of the method and:
 - For every initialization, sets the usage state of the initialized variable with the usage state of the value
 - For every call, changes the current usage state of the object the method was called
- Determines the usage state of the return type using the postconditions

Work summary

In short, the algorithm does the following:

- Generates typestates from the code equipped with assertions
- Translates the typestates into usage types
- Infers the correct usage state for each declared object

Work summary

In short, the algorithm does the following:

- Generates typestates from the code equipped with assertions
- Translates the typestates into usage types
- Infers the correct usage state for each declared object
- We implemented the algorithm:

http://usinfer.sourceforge.net/

Conclusion

Assertions

- If the assertions are not correct, one of two things might happen:
 - The tool fails to infer the usage types
 - The tool produces usage types that may allow unwanted behaviour In that case, typechecking the code with such usage may fail, if it allows erroneous behaviour

Conclusion

Assertions

- If the assertions are not correct, one of two things might happen:
 - The tool fails to infer the usage types
 - The tool produces usage types that may allow unwanted behaviour In that case, typechecking the code with such usage may fail, if it allows erroneous behaviour
- Thus, the algorithm can also be used to verify the correctness of the assertions

Future work

Correctness

We want to:

- State the intended results
- Prove the algorithm sound

Future work

Correctness

We want to:

- State the intended results
- Prove the algorithm sound

Assertions

Programming with assertions is also hard

We want to infer them as automatically as possible

Thank you